Technical Data Sheet



F3E0K11A



Load Cell, 3-axial

Location: Seat Pan

Force direction F_x, F_v, F_z

Application

Measuring of seat forces

Equivalent types
Customized version

Measurement specification Resistive Strain gauges

Options

ID-Module integrated in sensor

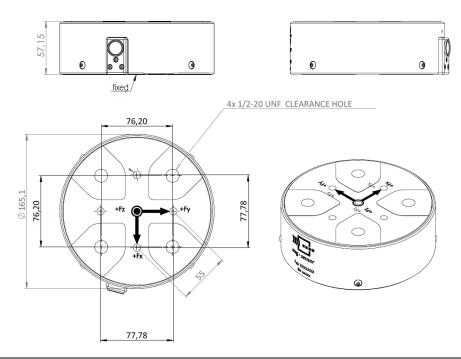


Technical description

The applied force causes compression or strain of the base body. The deformation is measured using strain gauges. The wiring of multiple strain gauges for a full bridge circuit compensates for the temperature influence on the zero signal and the cross-influence from other force and torque application.



Dimensions



mg·sensor Pure precision

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Technical specification

	Unit	Value		
		F _x	F _y	F _z
Measuring range	kN	45	45	45
Sensitivity ¹⁾	μV/V/kN	33.3	33.3	20
Output signal ^{1), 2)}	mV/V	1.5	1.5	0.9
Bridge resistance	Ω	350	350	700
Zero signal ¹⁾	mV/V	≤ 0.05		
Amplitude non-linearity ³⁾	%	≤ 1.0		
Hysteresis ³⁾	%	≤ 1.0		
Channel cross talk ³⁾	%	≤ 5.0		
Supply voltage	V	2–15		
Ultimate load	%	150		
Insulation resistance	ΜΩ	> 100		
Temperature range	°C	-30+70		
Weight (approximate)	g	6900		

All values measured at 10 V sensor supply voltage and at 23 °C.

¹⁾ Typical value

²⁾ At nominal load

³⁾ Relative nominal range